

Developers' Report Manual - CEMRACS 2007 a posteriori estimator

Radek Fučík, Ibrahim Cheddadi

1 List of Files

The a posteriori estimates are coded in FreeFEM++ using dynamic loading (see FreeFEM++ manual how to compile the code).

1.1 Source code

- Makefile
Scriptfile containing information how to build cemracs module (invoked by make command).
- cemracs2007.cpp
CEMRACS 2007 a posteriori estimate class.
- cemracs2007cl.cpp
Implementation of the classical error estimate.
- cemracs2007aux.cpp
Auxiliary functions needed for both cemracs2007.cpp and cemracs2007cl.cpp files.

1.2 Script files

- L.edp
L-Shape test problem - pure diffusion case (run by FreeFEM++ L.edp)
- SQ.edp
Square test problem - reaction-diffusion case (run by FreeFEM++ SQ.edp)

2 FreeFEM++ functions

2.1 cemracs2007

- AposterioCemracs2007() function Syntax:

```
load "cemracs2007";
AposterioCemracs2007(
    Th, [u, dx(u), dy(u), rhs, u0 u0dx, u0dy, react],
    filename="name of output file",
    output=[ etak[], etav[], etaDF[], etaR[], errk[], errv[],
            hd[], etaDF1[], etaDF2[] ],
    medit=MeditExport, strategy=Strategy);
```

Description:

- Th [mesh] ... FreeFEM++ mesh
- u [fespace(Th, P1)] ... numerical solution on Th

- dx(u) ... partial derivative $\partial u / \partial x$
- dy(u) ... partial derivative $\partial u / \partial y$
- rhs [func] right-hand side of the equation $-\Delta u + ru = f$ (i.e., the source term f)
- u0 [func] ... analytical solution
- u0dx [func] ... partial derivative of analytical solution $\partial u_0 / \partial x$
- u0dy [func] ... partial derivative of analytical solution $\partial u_0 / \partial y$
- react [func] ... reaction term r in $-\Delta u + ru = f$
- filename [string] ... name of the output file
- output [array] ... array of output vectors
 - * etak[] [fespace (Th, P0)] ... estimated error per triangles (for visualization purposes)
 - * etav[] [fespace (Th, P1)] ... estimated error per vertices
 - * etaDF[] [fespace (Th, P1)] ... estimator η_{DF}
 - * etaR[] [fespace (Th, P1)] ... estimator η_R
 - * errk[] [fespace (Th, P0)] ... exact energy error per triangles computed from the exact solution (u0, u0dx, u0dy) and numerical solution u, dx (u) , dy (u)
 - * errv[] [fespace (Th, P1)] ... exact energy error per vertices computed from the exact solution (u0, u0dx, u0dy) and numerical solution u, dx (u) , dy (u)
 - * hd[] [fespace (Th, P1)] ... characteristic length of mesh Th distribution (per vertex) - used for adaptation of mesh
 - * etaDF1[] [fespace (Th, P1)] ... estimator $\eta_{DF}^{(1)}$
 - * etaDF2[] [fespace (Th, P1)] ... estimator $\eta_{DF}^{(2)}$
- medit [int] ... indicates if medit output files are created [1=yes, 0=no]
- strategy [int] ... indicates which estimator t_h computation strategy is used (see cemracs2007.cpp):
 - * 0 : "jump" strategy
 - * 1 : minimization of $\eta_{DF}^{(1)2} + \eta_R^2$ strategy
 - * 2 : minimum of "jump" and minimization of $\eta_{DF}^{(1)2} + \eta_R^2$ strategy
 - * 3 : minimization of $\eta_{DF}^2 + \eta_R^2$ strategy
 - * 4 : minimum of all strategies (0,1,2,3 and 5)
 - * 5 : prescription of t_h such that η_R vanishes

3 Brief description of internal functions (source code)

3.1 cemracs2007.cpp

- double rhs_reaction(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)

Returns the value of $f - rp_h$ (given as argument in the FreeFEM++ script) at the point of coordinates (x, y) .

- double reaction(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)

Returns the value of the reaction function r (given as argument in the FreeFEM++ script) at the point of coordinates (x, y) .

- `double ex(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)`
Returns the value of the exact solution (given as argument in the FreeFEM++ script) at the point of coordinates (x, y) .
- `double ex_dx(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)`
Returns the value of the first partial derivative after x of the exact solution (given as argument in the FreeFEM++ script). at the point of coordinates (x, y) .
- `double ex_dy(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)`
Returns the value of the first partial derivative after y of the exact solution (given as argument in the FreeFEM++ script) at the point of coordinates (x, y) .
- `double ph_dx(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)`
Returns the value of the first partial derivative after x of the numerical solution (given as argument in the FreeFEM++ script) at the point of coordinates (x, y) .
- `double ph_dy(double x, double y, MeshPoint* mp, vector<Expression> sol, Stack &stack)`
Returns the value of the first partial derivative after y of the numerical solution (given as argument in the FreeFEM++ script) at the point of coordinates (x, y) .
- `double compute_m_D_square(double C_F_or_C_P, double h_D, double c_r)`
Returns the constant m_D^2 .
- `double compute_trace_constant(double edge_length, double h_K, double area)`
Returns the trace constant C_t .
- `double compute_m_K(double C_F_or_C_P, double h_K, double c_r)`
Returns the constant m_K .
- `double compute_m_K_tilde(double h_K, double c_r)`
Returns the constant \tilde{m}_K .
- `double qformula_exact_uni(double x1, double y1, double x2, double y2, double x3, double y3, MeshPoint* mp, vector<Expression> sol, Stack &stack)`
Returns the value of $\int_K ((\partial_x p_h - \partial_x p)^2 + (\partial_y p_h - \partial_y p)^2) dx$ on a triangle K given by the coordinates $(x_1, y_1), \dots$ of its vertices, where p is the exact solution. The integral is evaluated by a quadrature formula.
- `double qformula_DF(double x1, double y1, double x2, double y2, double x3, double y3, double alpha, double beta, double gamma, double gradphx, double gradphy, double aireK)`

Returns the value of $\int_K ((\partial_x p_h + \mathbf{t}_h^x)^2 + (\partial_y p_h + \mathbf{t}_h^y)^2) dx$ on a triangle K given by the coordinates $(x_1, y_1), \dots$ of its vertices. The integral is evaluated by a quadrature formula.

- `double qformula_R_uni_react(double x1, double y1, double x2, double y2, double x3, double y3, double alpha, double beta, double gamma, double aireK, MeshPoint* mp, vector<Expression> sol, Stack &stack)`

Returns the value of $\int_K (f - r p_h - \nabla \cdot \mathbf{t}_h)^2 dx$ on a triangle K given by the coordinates $(x_1, y_1), \dots$ of its vertices. The integral is evaluated by a quadrature formula.

- `void tridiag_solver(int N, double *a, double *b, double *c, double *f, double *y)`

Computes in `double *y` the solution of a tridiagonal system where ... (*Radek you may know*)

- `int cemracs_solver(int nu, double *alpha, double *beta, double *gamma, double *phi, double *upsilon)`

(*Radek you may know*)

- `void compute_matrix_int_tri(double *a, double *b, double *c, double *f, double **E_coef, int N)`

Assembles the tridiagonal matrix (in `double *a, double *b, double *c`: as in `tridiag_solver`) and the vector (`double *f`) corresponding to the quadratic form that is to be minimized in the case of an interior dual volume.

- `void compute_matrix_ext_tri(double *a, double *b, double *c, double *f, double **E_coef, int N, double E10t, double E4n2t, double E1n2t)`

Assembles the tridiagonal matrix (in `double *a, double *b, double *c`: as in `tridiag_solver`) and the vector (`double *f`) corresponding to the quadratic form that is to be minimized in the case of an exterior dual volume.

- `void compute_X0(double *X0, double vx, double vy, int N, double **A_triangle_coor, MeshPoint* mp, vector<Expression> sol, Stack &stack, int boundary)`

Computes the vector `double *X0` of the prescribed coefficients α_0 for each subtriangle. `X0[i]` contains α_0^i (*is it right ?*).

- `void compute_coef_1(int i, double **Res_coef, double **Diff_coef, double **E_coef, double **alpha_tab, MeshPoint* mp, vector<Expression> sol, Stack &stack, double xx0, double yy0, double xx1, double yy1, double xx2, double yy2, double gx, double gy, double mD2)`

Computes for the i -th subtriangle (given by the coordinates $(xx0, yy0), \dots$ of its vertices) the corresponding part of the coefficients array `double **E_coef` that is used for assembling the matrix and the linear part of the quadratic form $\eta_R^2 + \left(\eta_{DF}^{(1)}\right)^2$.

- `void compute_coef_2(int i, double **Res_coef, double **Diff_coef, double **E_coef, double **alpha_tab, MeshPoint* mp, vector<Expression> sol, Stack &stack, double xx0, double yy0, double xx1, double yy1, double xx2, double yy2, double gx, double gy, double mD2, double C_F_or_C_P, double c_r)`

Computes for the i -th subtriangle (given by the coordinates $(xx0,yy0),\dots$ of its vertices) the corresponding part of the coefficients array `double **E_coef` that is used for assembling the matrix and the linear part of the quadratic form $\eta_R^2 + \left(\eta_{DF}^{(2)}\right)^2$.

- `void compute_grad_ph(int i, double &gx, double &gy, double vx, double vy, double **A_triangle_coor, MeshPoint* mp, vector<Expression> sol, Stack &stack)`

Computes in `double &gx, double &gy` the constant value of ∇p_h on the i -th triangle.

- `double compute_estimators(double** alpha_tab, double C_F_or_C_P, double **A_triangle_coor, double vx, double vy, int n_big_tria,MeshPoint* mp, vector<Expression> sol, Stack &stack, int boundary, double &est_DF, // square root of the DF estimator double &est_R, // square root of the R estimator double &est_DF_1, // square root of the DF_1 estimator double &est_DF_2 // square root of the DF_2 estimator)`

Computes the values of the estimators from t_h , given the array of its coefficients `double** alpha_tab`.

- `void compute_alpha_tab_from_X(double **alpha_tab, double alpha1, double alpha2, double *X, int n_big_tria, int boundary)`

Computes `double **alpha_tab`, where `alpha_tab[i][j]` contains α_j^i , from the solution `double *X` of the minimization problem.

- `void compute_alpha0(double **alpha_tab, int n_big_tria, double **A_triangle_coor, double vx, double vy, MeshPoint* mp, vector<Expression> sol, Stack &stack)`

Adds in `double **alpha_tab` the values of α_0^i .

- `void compute_th_minimization_1(double **alpha_tab, int n_big_tria, double **A_triangle_coor, double vx, double vy, MeshPoint* mp, vector<Expression> sol, Stack &stack, int boundary, double C_F_or_C_P)`

Performs the minimization process of $\eta_R^2 + \left(\eta_{DF}^{(1)}\right)^2$. The output is the array `double** alpha_tab` of the coefficients of t_h .

- `void compute_th_minimization_2(double **alpha_tab, int n_big_tria, double **A_triangle_coor, double vx, double vy, MeshPoint* mp, vector<Expression> sol, Stack &stack,`

```

    int boundary, double C_F_or_C_P
)

```

Performs the minimization process of $\eta_R^2 + (\eta_{DF}^{(2)})^2$. The output is the array `double** alpha_tab` of the coefficients of t_h .

- `void compute_th_jumping(double **alpha_tab, int n_big_tria, double **A_triangle_coor, double vx, double vy, MeshPoint* mp, vector<Expression> sol, Stack &stack, int boundary, double C_F_or_C_P)`

Computes the t_h with the “jump” strategy (no minimization process).

3.2 cemracs2007aux.cpp

- `void intersection(double a1, double a2, double b1, double b2, double c1, double c2, double d1, double d2, double &x1, double &x2)`

Returns coordinates of an intersection $[x_1, x_2]$ of two lines that are given by points $[a_1, a_2], [b_1, b_2]$ and the other by $[c_1, c_2], [d_1, d_2]$.

- `double distance(double a1, double a2, double b1, double b2)`

Returns the distance between two points.

- `void barycenter(double &x1, double &x2, double a1, double a2, double b1, double b2, double c1, double c2)`

Computes the barycenter $[x_1, x_2]$ of a triangle.

- `double angle(double a1, double a2, double b1, double b2, double c1, double c2)`

Computes the angle between vectors $[c_1, c_2], [a_1, a_2]$ and $[c_1, c_2], [b_1, b_2]$.

- `double vectorangle(double u1, double u2)`

Returns the argument of a vector (u_1, u_2) .

- `int compute_angle_interval(double &angle_d, double &angle_u, double c1, double c2, double a1, double a2, double b1, double b2)`

Returns the interval of internal angles corresponding to the vertex $[c_1, c_2]$.

- `int isin(double u, double a1, double a2)`

Indicates, if an angle u is between a_1 and a_2 .

- `int interval_intersection(double &x1, double &x2, double a1, double a2, double b1, double b2)`

Intersects two angle intervals together.

- `int is_intersection_nonempty(int ne, int n, int k, double **T_d, double **T_u, int **T_is, double lower, double upper)`

Indicates if the intersection of a set of angle intervals is non-empty.

- `int iscondition27(int n, double **A_triangle_coor, double v1, double v2, int ne, double **A_edges)`
Indicates, if the condition !!!!!!!!!!!!!
- `int isconvex(int nt, double **A_triangle_coor, double v1, double v2, int boundary)`
Indicates if the dual volume is convex.
- `double compute_C_P(int n, double **A_triangle_coor, double v1, double v2, int boundary)`
Computes the Poincare constant.
- `double compute_diameter(int n, double **A, double v1, double v2)`
Computes diameter of the dual volume.
- `double compute_minimal_diameter(int n, double **A, double v1, double v2)`
Determines the minimal diameter of dual volumes.
- `double area_K(double x1, double y1, double x2, double y2, double x3, double y3)`
Computes the area of a triangle.
- `double compute_max_edge_triangle(double x1, double y1, double x2, double y2, double x3, double y3)`
Determine the longest edge of a triangle.
- `double compute_min_edge_triangle(double x1, double y1, double x2, double y2, double x3, double y3)`
Determine the shortest edge of a triangle.
- `double compute_C_F(int n, double **A, double v1, double v2, int boundary)`
Compute the Friedrichs constant.

4 Example FreeFEM++ scripts

4.1 diff.edp

Classical L shape domain problem, $\Delta u = 0$.

```
// load cemracs -module
load "cemracs2007";

// the classical L space problem
border a(t=-1,1){x=t; y=-1; label=1;};
border b(t=-1,0){x=1; y=t; label=2;};
border c(t=0,1){x=1-t; y=0; label=3;};
border d(t=0,1){x=0; y=t; label=4;};
border e(t=0,1){x=-t; y=1; label=5;};
```

```

border f(t=-1,1){x=-1; y=-t; label=6;};
mesh Th=buildmesh(a(4)+ b(2) + c(2) + d(2) + e(2) + f(4));

// FE SPACES DEFINITION
fespace Vh(Th,P1); // the solution
fespace Pvh(Th,P1); // the indicator in each vertex
fespace Pth(Th,P0); // the indicator in each triangle

// FE approximations
Vh u,v;

// EXACT SOLUTION DEFINITION
func real tita(real t) // atan2 continuous in y=0 :
{
real q=0;
if (t<=0) q=t+2*pi;
if (t>0) q=t;
return q;
};
// exact solution function
func u0=sin((2.0/3.0)*tita(atan2(y,x)))*(x^2+y^2)^(1.0/3.0);
// exact solution derivative du0/dx
func u0dx=
(2.0/3.0)*((x*x + y*y)^(-2.0/3.0))*(x*sin(2.0/3.0*tita(atan2(y,x)))-
y*cos(2.0*tita(atan2(y,x))/3.0));
// exact solution derivative du0/dy
func u0dy=
(2.0/3.0)*((x*x + y*y)^(-2.0/3.0))*(y*sin(2.0*tita(atan2(y,x))/3.0)+
x*cos(2.0*tita(atan2(y,x))/3.0));
// reaction term (zero in this case)
func react=0;
// right hand side of the laplace equation (source term)
func rhs= 0;

// FE PROBLEM
problem Laplace(u,v)=
int2d(Th) (u*v*react + dx(u)*dx(v) + dy(u)*dy(v))-int2d(Th) (rhs*v)
+on(1,2,3,4,5,6,u=u0);

for (int i=0;i<10;i++) // refining the mesh
{
u=u;
Laplace;

// ESTIMATOR VARIABLES
Pvh etav; // squares of final estimator (per vertex)
Pvh etaDF; // squares of DF part of the estimator
Pvh etaR; // squares of R part of the estimator

```



```

Pvh errv;    // squares of computed error (per vertex)
Pvh hd;     // computed mesh size
Pvh etaDF1; // squares of DF(1) part of the est.
Pvh etaDF2; // squares of DF(2) part of the est.
Pth etak;   // squares of final estimator (per triangle)
Pth errk;   // squares of computed error (per triangle)

int estimator = 0;
// 0 ... jump estimator
// 1 ... minimal estimator
// 2 ... minimum of jump and minimal estimator
AposterioroCemracs2007(
  Th,[u, dx(u), dy(u), rhs, u0, u0dx, u0dy, react],
  filename="filename",
  output=[etak[],etav[],etaDF[],etaR[],errk[],errv[],hd[],etaDF1[],etaDF2[]],
  medit=0,
  strategy=estimator);

real exacterror = sqrt(errv[].sum); // exact error estimator
real estDF = sqrt(etaDF[].sum);    // DF part of estimator
real estR  = sqrt(etaR[].sum);     // R part of estimator
real est   = sqrt(etav[].sum);     // estimated error

cout << "Estimated error " << est << " Exact error " << exacterror << endl;

// REGULAR GRID REFINEMENT
Th=trunc(Th,1,split=2);
}

```

4.2 react.edp

Square domain problem, $\Delta u + ru = 0$.

```

// load cemracs module
load "cemracs2007";

// SQUARE PROBLEM
mesh Th=square(2,4,[x,y]);

// FE SPACES DEFINITION
fespace Vh(Th,P1); // the solution
fespace Pvh(Th,P1); // the indicator in each vertex
fespace Pth(Th,P0); // the indicator in each triangle

// FE approximations
Vh u,v;

```

```

// EXACT SOLUTION DEFINITION
// reaction term
func react=10e6;
// exact solution function
func u0=exp(-sqrt(react)*x)+exp(-sqrt(react)*y);
// exact solution derivative du0/dx
func u0dx=-sqrt(react)*exp(-sqrt(react)*x);
// exact solution derivative du0/dy
func u0dy=-sqrt(react)*exp(-sqrt(react)*y);
// right hand side of the laplace equation (source term)
func rhs= 0;

// FE PROBLEM
problem Laplace(u,v)=
  int2d(Th) (u*v*react + dx(u)*dx(v) + dy(u)*dy(v)) -int2d(Th) (rhs*v)
  +on(1,2,3,4,u=u0);

for (int i=0;i<10;i++) // refining the mesh
{
  u=u;
  Laplace;

  // ESTIMATOR VARIABLES
  Pvh etav; // squares of final estimator (per vertex)
  Pvh etaDF; // squares of DF part of the estimator
  Pvh etaR; // squares of R part of the estimator
  Pvh errv; // squares of computed error (per vertex)
  Pvh hd; // computed mesh size
  Pvh etaDF1; // squares of DF(1) part of the est.
  Pvh etaDF2; // squares of DF(2) part of the est.
  Pth etak; // squares of final estimator (per triangle)
  Pth errk; // squares of computed error (per triangle)

  int estimator = 0;
  // 0 ... jump estimator
  // 1 ... minimal estimator
  // 2 ... minimum of jump and minimal estimator
  AposterioCemracs2007(
    Th,[u, dx(u), dy(u), rhs, u0, u0dx, u0dy, react],
    filename="filename",
    output=[etak[],etav[],etaDF[],etaR[],errk[],errv[],hd[],etaDF1[],etaDF2[]],
    medit=0,
    strategy=estimator);

  real exacterror = sqrt(errv[].sum); // exact error estimator

```

```
real estDF = sqrt(etaDF[].sum); // DF part of estimator
real estR  = sqrt(etaR[].sum); // R part of estimator
real est   = sqrt(etav[].sum); // estimated error

cout << "Estimated error " << est << " Exact error " << exacterror << endl;

// REGULAR GRID REFINEMENT
Th=trunc(Th,1,split=2);
}
```

4.3 General usage

You need to have the `cemracs2007.so` in the same directory as the script files in order to execute `diff.edp` or `react.edp` scripts. Then, execute the scripts as follows

```
FreeFEM++ diff.edp
FreeFEM++ react.edp
```